## Quantum Mechanics: Vibration and Rotation of Molecules

## 8th April 2009

## I. The Rigid Rotor and Q. M. Orbital Angular Momentum

Consider a **rigid** rotating *diatomic* molecule -- the rigid rotor -- with two masses separated by a distance  $r_o$ ; the distance is fixed, and the rotation occurs in the absence of external potentials. The quantum mechanical description begins with the Hamiltonian:

$$\hat{H} = \hat{K} + V(x, y, z) = \frac{-\hbar^2}{2\mu} \nabla^2 + 0$$
$$\nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$$

This is simply the kinetic energy operator as we have seen in the past for the particle-in-box and the harmonic oscillator. Now, we can change coordinate systems from Cartesian to polar spherical coordinates. This goes as:

 $Cartesian(x, y, z) \rightarrow spherical polar(r, \theta, \phi)$ 

$$x = rsin\theta cos\phi$$

$$y = rsin\theta sin\phi$$

$$z = r cos \theta$$

$$\nabla^2 = \frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial}{\partial r} \right) + \frac{1}{r^2 sin\theta} \frac{\partial}{\partial \theta} \left( sin\theta \frac{\partial}{\partial \theta} \right) + \frac{1}{r^2 sin^2 \theta} \frac{\partial^2}{\partial \phi^2}$$

Thus, in spherical polar coordinates,  $\hat{H}(r,\theta,\phi)\psi(r,\theta,\phi) = E\psi(r,\theta,\phi)$  becomes:

$$\left[\frac{-\hbar^2}{2\mu}\left(\frac{1}{r^2}\frac{\partial}{\partial r}\left(r^2\frac{\partial}{\partial r}\right) + \frac{1}{r^2sin\theta}\frac{\partial}{\partial \theta}\left(sin\theta\frac{\partial}{\partial \theta}\right) + \frac{1}{r^2sin^2\theta}\frac{\partial^2}{\partial \phi^2}\right)\right]\psi(r,\theta,\phi) = E\psi(r,\theta,\phi)$$

For the **rigid** rotor, the length between masses is constant. Thus

$$\psi(r,\theta,\phi) \longrightarrow \psi(r_o,\theta,\phi) \longrightarrow \frac{\partial}{\partial r}\psi = 0$$

The Schrodinger equation is now:

$$\left[\frac{-\hbar^2}{2\mu r_o^2} \left(\frac{1}{\sin\theta} \frac{\partial}{\partial\theta} \left(\sin\theta \frac{\partial}{\partial\theta}\right) + \frac{1}{\sin^2\theta} \frac{\partial^2}{\partial\phi^2}\right)\right] \psi(r,\theta,\phi) = E\psi(r,\theta,\phi)$$

Recall:  $\mu r_0^2 = I$ , the moment of Inertia of the rotor.

$$\left[\frac{-\hbar^2}{2I}\left(\frac{1}{\sin\theta}\frac{\partial}{\partial\theta}\left(\sin\theta\frac{\partial}{\partial\theta}\right) + \frac{1}{\sin^2\theta}\frac{\partial^2}{\partial\phi^2}\right)\right]\psi(r,\theta,\phi) = E\psi(r,\theta,\phi)$$

If we assume that  $\psi(r_o, \theta, \phi)$  is more generally  $\psi(r_o, \theta, \phi) = B(r)Y(\theta, \phi)$ (the function B(r) is some generic function that takes into account the true r-dependence which we are simplifying in the present case by treating the system as a rigid rotor), the problem reduces to:

$$\left[\frac{-\hbar^2}{2I}\left(\frac{1}{\sin\theta}\frac{\partial}{\partial\theta}\left(\sin\theta\frac{\partial}{\partial\theta}\right) + \frac{1}{\sin^2\theta}\frac{\partial^2}{\partial\phi^2}\right)\right]Y(\theta,\phi) = EY(\theta,\phi)$$

## Solving the Rigid Rotor Problem

Rearranging the previous equation:

$$\left[sin\theta\frac{\partial}{\partial\theta}\left(sin\theta\frac{\partial}{\partial\theta}\right) + \frac{2IE}{\hbar^2}sin^2\theta\right]Y(\theta,\phi) = -\frac{\partial^2}{\partial\phi^2}Y(\theta,\phi)$$

The left-hand side of the previous equation is a function only of  $\theta$  and the right is a function only of  $\phi$ . Thus, we can use *separation of variables* to generate a solution:

$$Y(\theta,\phi) = \Theta(\theta)\Phi(\phi) \quad \rightarrow \quad Define: \quad \beta \equiv \frac{2IE}{\hbar^2}$$

Thus,

$$\left[\sin\theta\frac{\partial}{\partial\theta}\left(\sin\theta\frac{\partial}{\partial\theta}\right) + \frac{2IE}{\hbar^2}\sin^2\theta\right]\Theta(\theta)\Phi(\phi) = -\frac{\partial^2}{\partial\phi^2}\Theta(\theta)\Phi(\phi)$$

Dividing by  $\Theta(\theta)\Phi(\phi)$  and simplifying:

$$\left[\frac{\sin\theta}{\Theta(\theta)}\frac{\partial}{\partial\theta}\left(\sin\theta\frac{\partial}{\partial\theta}\right)\Theta(\theta)+\beta\sin^2\theta\right]=-\frac{1}{\Phi(\phi)}\frac{\partial^2}{\partial\phi^2}\Phi(\phi)$$

Since both sides are functions of different variables, each is equal to a constant, which we'll let be  $m^2$ .

$$\frac{1}{\Phi(\phi)}\frac{\partial^2}{\partial\phi^2}\Phi(\phi) = -m^2$$

$$\frac{\sin\theta}{\Theta(\theta)}\frac{\partial}{\partial\theta}\left(\sin\theta\frac{\partial}{\partial\theta}\right)\Theta(\theta) + \beta\sin^2\theta = m^2$$

First consider the  $\phi$  expression:

$$\frac{\partial^2}{\partial \phi^2} \Phi(\phi) = -m^2 \Phi(\phi)$$

Solutions are of the general form:  $\Phi_{\pm}(\phi) = A_{\pm}e^{\pm im\phi}$ . As before, the boundary conditions lead to quantization. Since this expression is related to the z-component of the angular momentum, we can imagine the particle moving along a circular ring. At the values of  $\phi$  separated by an entire revolution, the wavefunction has to be the same; i.e.  $\Phi(\phi) = \Phi(\phi + 2\pi)$ .

The latter constraint leads to:  $e^{\pm i2\pi m} = 1$ . This is valid for values of m:

$$m = 0, \pm 1, \pm 2, \pm 3, \dots$$

m is the magnetic quantum number. Thus :

$$\Phi(\phi) = A_m e^{im\phi}$$
  $m = 0, \pm 1, \pm 2, \pm 3, \dots$ 

Normalization gives:

$$\Phi(\phi) = \frac{1}{\sqrt{2\pi}} e^{im\phi} \qquad m = 0, \pm 1, \pm 2, \pm 3, \dots$$

Now we'll consider the  $\Theta$  function:

$$\frac{\sin\theta}{\Theta(\theta)}\frac{\partial}{\partial\theta}\left(\sin\theta\frac{\partial}{\partial\theta}\right)\Theta(\theta) + \beta\sin^2\theta = m^2$$

First change variables:  $x = \cos\theta$ ,  $\Theta(\theta) = P(x)$ , and  $\frac{dx}{-\sin\theta} = d\theta$ .

Since  $0 \le \theta \le \pi$ ,  $-1 \le x \le 1$ , conveniently. Also,  $\sin^2 \theta = 1 - \cos^2 \theta = 1 - x^2$ . After some rearrangement and simplification, one obtains the associated Legendre equation:

$$\left(1 - x^2\right)\frac{d^2}{dx^2}P(x) - 2x\frac{d}{dx}P(x) + \left[\beta - \frac{m^2}{1 - x^2}\right]P(x) = 0$$

The boundary conditions arise due to the requirement that  $\Theta$  is continuous; this quantizes  $\beta$ :

$$\beta = l(l+1); \quad l = 0, 1, 2, 3, \dots \quad (with \ m \ = \ 0, \pm 1, \pm 2, \pm 3, \dots)$$

The energy (eigenvalue) is thus quantized from the definition of  $\beta$ .

$$E = \frac{\hbar^2}{2I}l(l+1) \qquad l = 0, 1, 2, 3, \dots$$

The wavefunctions are the associated Legendre Polynomials,  $P_l^{|m|}$ :

$$P_l^{|m|}(x) = P_l^{|m|}(\cos\theta)$$
$$P_0^0(\cos\theta) = 1 \qquad P_1^0(\cos\theta) = \cos\theta$$
$$P_2^0(\cos\theta) = \frac{1}{2} \left(3\cos^2\theta - 1\right) \qquad P_2^1(\cos\theta) = 3\cos\theta\sin\theta$$

Putting things togeher:

$$\Theta(\theta) = A_{lm} P_l^{|m|}(\cos\theta)$$

From normalization:

$$A_{lm} = \left[ \left( \frac{2l+1}{2} \right) \frac{(l-|m|)!}{(l+|m|)!} \right]^{1/2} \quad \leftarrow \quad 1 = A_{lm}^2 \int_o^{\pi} \left[ P_l^{|m|}(\cos\theta) \right]^2 \sin\theta d\theta$$

The Spherical Harmonics are the eigenfunctions for the 3-D rigid rotor:

$$Y_l^m = \left[ \left(\frac{2l+1}{4\pi}\right) \frac{(l-|m|)!}{(l+|m|)!} \right]^{1/2} P_l^{|m|}(\cos\theta) e^{im\phi} \quad (\hat{H}Y = EY) \quad \left(E_l = \frac{\hbar^2}{2I} l(l+1)\right)$$

But what is the relation between the l and m quantum numbers that have arisen? For this, we need to consider Angular Momentum