E04KCF - NAG Fortran Library Routine Document

Note. Before using this routine, please read the Users' Note for your implementation to check the interpretation of bold italicised terms and other implementation-dependent details.

1 Purpose

E04KCF is an easy-to-use modified-Newton algorithm for finding a minimum of a function $F(x_1, x_2, ..., x_n)$, subject to fixed upper and lower bounds on the independent variables $x_1, x_2, ..., x_n$, when first derivatives of F are available. It is intended for functions which are continuous and which have continuous first and second derivatives (although it will usually work even if the derivatives have occasional discontinuities).

2 Specification

```
SUBROUTINE E04KCF(N, IBOUND, BL, BU, X, F, G, IW, LIW, W, LW, IFAIL)

INTEGER N, IBOUND, IW(LIW), LIW, LW, IFAIL

real BL(N), BU(N), X(N), F, G(N), W(LW)
```

3 Description

This routine is applicable to problems of the form:

```
\mbox{Minimize}\, F(x_1,x_2,\ldots,x_n) \mbox{ subject to } l_j \leq x_j \leq u_j, \quad \  j=1,2,\ldots,n
```

when first derivatives are known.

Special provision is made for problems which actually have no bounds on the x_j , problems which have only non-negativity bounds, and problems in which $l_1 = l_2 = \ldots = l_n$ and $u_1 = u_2 = \ldots = u_n$. The user must supply a routine FUNCT2 to calculate the values of F(x) and its first derivatives at any point x.

From a starting point supplied by the user there is generated, on the basis of estimates of the gradient of the curvature of F(x), a sequence of feasible points which is intended to converge to a local minimum of the constrained function.

4 References

[1] Gill P E and Murray W (1976) Minimization subject to bounds on the variables NPL Report NAC 72 National Physical Laboratory

5 Parameters

1: N — INTEGER Input

On entry: the number n of independent variables.

Constraint: $N \ge 1$.

2: IBOUND — INTEGER

Inpu

On entry: indicates whether the facility for dealing with bounds of special forms is to be used. It must be set to one of the following values:

IBOUND = 0

if the user will be supplying all the l_j and u_j individually.

IBOUND = 1

if there are no bounds on any x_i .

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IBOUND = 2

if all the bounds are of the form $0 \le x_i$.

IBOUND = 3

if
$$l_1 = l_2 = \ldots = l_n$$
 and $u_1 = u_2 = \ldots = u_n$.

Constraint: $0 \leq IBOUND \leq 3$.

3: $BL(N) - real \operatorname{array}$

Input/Output

On entry: the lower bounds l_i .

If IBOUND is set to 0, the user must set BL(j) to l_j , for j = 1, 2, ..., n. (If a lower bound is not specified for a particular x_i , the corresponding BL(j) should be set to -10^6 .)

If IBOUND is set to 3, the user must set BL(1) to l_1 ; E04KCF will then set the remaining elements of BL equal to BL(1).

On exit: the lower bounds actually used by E04KCF.

4: BU(N) - real array

Input/Output

On entry: the upper bounds u_i .

If IBOUND is set to 0, the user must set $\mathrm{BU}(j)$ to u_j , for $j=1,2,\ldots,n$. (If an upper bound is not specified for a particular x_j , the corresponding $\mathrm{BU}(j)$ should be set to 10^6 .)

If IBOUND is set to 3, the user must set BU(1) to u_1 ; E04KCF will then set the remaining elements of BU equal to BU(1).

On exit: the upper bounds actually used by E04KCF.

5: X(N) - real array

Input/Output

On entry: X(j) must be set to a guess at the jth component of the position of the minimum, for j = 1, 2, ..., n. The routine checks the gradient at the starting point, and is more likely to detect any error in the user's programming if the initial X(j) are non-zero and mutually distinct.

On exit: the lowest point found during the calculations of the position of the minimum.

6: F — *real*

Output

On exit: the value of F(x) corresponding to the final point stored in X.

7: $G(N) - real \operatorname{array}$

Output

On exit: the value of $\frac{\partial F}{\partial x_j}$ corresponding to the final point stored in X, for j = 1, 2, ..., n; the value of G(j) for variables not on a bound should normally be close to zero.

8: IW(LIW) — INTEGER array

Workspace

9: LIW — INTEGER

Input

On entry: the length of IW, as declared in the (sub)program from which E04KCF is called.

Constraint: LIW \geq N + 2.

10: W(LW) - real array

Workspace

11: LW — INTEGER

Input

On entry: the length of W, as declared in the (sub)program from which E04KCF is called.

Constraint: LW $\geq \max(N \times (N+7), 10)$

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12: IFAIL — INTEGER

Input/Output

On entry: IFAIL must be set to 0, -1 or 1. Users who are unfamiliar with this parameter should refer to Chapter P01 for details.

On exit: IFAIL = 0 unless the routine detects an error or gives a warning (see Section 6).

For this routine, because the values of output parameters may be useful even if IFAIL $\neq 0$ on exit, users are recommended to set IFAIL to -1 before entry. It is then essential to test the value of IFAIL on exit. To suppress the output of an error message when soft failure occurs, set IFAIL to 1.

5.1 User-supplied Routines

1: FUNCT2 — SUBROUTINE, supplied by the user.

External Procedure

This routine must be supplied by the user to calculate the values of the function F(x) and its first derivatives $\frac{\partial F}{\partial x_j}$ at any point x. Since the routine is not a parameter to E04KCF, it **must** be called FUNCT2. It should be tested separately before being used in conjunction with E04KCF (see the the Chapter Introduction).

Its specification is:

```
SUBROUTINE FUNCT2(N, XC, FC, GC)
INTEGER N
real XC(N), FC, GC(N)
```

1: N — INTEGER

Input

On entry: the number n of variables.

2: $XC(N) - real \operatorname{array}$

Input

On entry: the point x at which the function and derivatives are required.

3: FC-real

Output

On exit: the value of the function F at the current point x,

4: GC(N) — real array

Output

On exit: GC(j) must be set to the value of the first derivative $\frac{\partial F}{\partial x_j}$ at the point x, for j = 1, 2, ..., n.

Parameters denoted as *Input* must **not** be changed by this procedure.

6 Error Indicators and Warnings

Errors or warnings specified by the routine:

IFAIL = 1

```
On entry, N < 1, or IBOUND < 0, or IBOUND > 3, or IBOUND = 0 and BL(j) > BU(j) for some j, or IBOUND = 3 and BL(1) > BU(1), or LIW < N + 2, or LW < max(10,N× (N+7)).
```

IFAIL = 2

There has been a large number of function evaluations, yet the algorithm does not seem to be converging. The calculations can be restarted from the final point held in X. The error may also indicate that F(x) has no minimum.

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IFAIL = 3

The conditions for a minimum have not all been met but a lower point could not be found and the algorithm has failed.

IFAIL = 4

Not used. (This value of the parameter is included to make the significance of IFAIL = 5 etc. consistent in the easy-to-use routines.)

IFAIL = 5

IFAIL = 6

IFAIL = 7

IFAIL = 8

There is some doubt about whether the point x found by E04KCF is a minimum. The degree of confidence in the result decreases as IFAIL increases. Thus, when IFAIL = 5 it is probable that the final x gives a good estimate of the position of a minimum, but when IFAIL = 8 it is very unlikely that the routine has found a minimum.

IFAIL = 9

In the search for a minimum, the modulus of one of the variables has become very large ($\sim 10^6$). This indicates that there is a mistake in FUNCT2, that the user's problem has no finite solution, or that the problem needs rescaling (see Section 8).

IFAIL = 10

It is very likely that the user has made an error in forming the gradient.

If the user is dissatisfied with the result (e.g., because IFAIL = 5, 6, 7 and 8), it is worth restarting the calculations from a different starting point (not the point at which the failure occurred) in order to avoid the region which caused the failure. If persistent trouble occurs and it is possible to calculate second derivatives it may be advisable to change to a routine which uses second derivatives (see the Chapter Introduction).

7 Accuracy

When a successful exit is made then, for a computer with a mantissa of t decimals, one would expect to get about t/2-1 decimals accuracy in x and about t-1 decimals accuracy in F, provided the problem is reasonably well scaled.

8 Further Comments

The number of iterations required depends on the number of variables, the behaviour of F(x) and the distance of the starting point from the solution. The number of operations performed in an iteration of E04KCF is roughly proportional to $n^3 + O(n^2)$. In addition, each iteration makes at least m + 1 calls of FUNCT2 where m is the number of variables not fixed on bounds. So unless F(x) and the gradient vector can be evaluated very quickly, the run time will be dominated by the time spent in FUNCT2.

Ideally the problem should be scaled so that at the solution the value of F(x) and the corresponding values of x_1, x_2, \ldots, x_n are in the range (-1, +1), and so that at points a unit distance away from the solution, F is approximately a unit value greater than at the minimum. It is unlikely that the user will be able to follow these recommendations very closely, but it is worth trying (by guesswork), as sensible scaling will reduce the difficulty of the minimization problem, so that E04KCF will take less computer time.

9 Example

A program to minimize

$$F = (x_1 + 10x_2)^2 + 5(x_3 - x_4)^2 + (x_2 - 2x_3)^4 + 10(x_1 - x_4)^4$$

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subject to

starting from the initial guess (3, -1, 0, 1). (In practice, it is worth trying to make FUNCT2 as efficient as possible. This has not been done in the example program for reasons of clarity.)

9.1 Program Text

Note. The listing of the example program presented below uses bold italicised terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```
E04KCF Example Program Text.
Mark 14 Revised. NAG Copyright 1989.
.. Parameters ..
INTEGER
                 N, LIW, LW
PARAMETER
                 (N=4,LIW=N+2,LW=N*(N+7))
INTEGER
                 NOUT
PARAMETER
                 (NOUT=6)
.. Local Scalars ..
real
                 F
INTEGER
                 IBOUND, IFAIL, J
.. Local Arrays ..
                 BL(N), BU(N), G(N), W(LW), X(N)
real
INTEGER
                 IW(LIW)
.. External Subroutines ..
EXTERNAL
                 E04KCF
.. Executable Statements ..
WRITE (NOUT,*) 'EO4KCF Example Program Results'
X(1) = 3.0e0
X(2) = -1.0e0
X(3) = 0.0e0
X(4) = 1.0e0
IBOUND = 0
BL(1) = 1.0e0
BU(1) = 3.0e0
BL(2) = -2.0e0
BU(2) = 0.0e0
X(3) is unconstrained, so we set BL(3) to a large negative
number and BU(3) to a large positive number.
BL(3) = -1.0e6
BU(3) = 1.0e6
BL(4) = 1.0e0
BU(4) = 3.0e0
IFAIL = 1
CALL EO4KCF(N, IBOUND, BL, BU, X, F, G, IW, LIW, W, LW, IFAIL)
IF (IFAIL.NE.O) THEN
   WRITE (NOUT,*)
   WRITE (NOUT, 99999) 'Error exit type', IFAIL,
     ' - see routine document'
END IF
IF (IFAIL.NE.1) THEN
   WRITE (NOUT,*)
   WRITE (NOUT, 99998) 'Function value on exit is ', F
   WRITE (NOUT,99998) 'at the point', (X(J),J=1,N)
   WRITE (NOUT,*)
```

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```
'the corresponding (machine dependent) gradient is'
         WRITE (NOUT, 99997) (G(J), J=1, N)
     END IF
     STOP
99999 FORMAT (1X,A,I3,A)
99998 FORMAT (1X,A,4F12.4)
99997 FORMAT (13X,4e12.4)
     END
     SUBROUTINE FUNCT2(N,XC,FC,GC)
     Routine to evaluate objective function and its 1st derivatives.
     This routine must be called FUNCT2.
      .. Scalar Arguments ..
     real
                        FC
     INTEGER
     .. Array Arguments ..
                        GC(N), XC(N)
     real
      .. Local Scalars ..
                        X1, X2, X3, X4
     real
      .. Executable Statements ..
     X1 = XC(1)
     X2 = XC(2)
     X3 = XC(3)
     X4 = XC(4)
     FC = (X1+10.0e0*X2)**2 + 5.0e0*(X3-X4)**2 + (X2-2.0e0*X3)**4 +
           10.0e0*(X1-X4)**4
     GC(1) = 2.0e0*(X1+10.0e0*X2) + 40.0e0*(X1-X4)**3
     GC(2) = 20.0e0*(X1+10.0e0*X2) + 4.0e0*(X2-2.0e0*X3)**3
     GC(3) = 10.0e0*(X3-X4) - 8.0e0*(X2-2.0e0*X3)**3
     GC(4) = -10.0e0*(X3-X4) - 40.0e0*(X1-X4)**3
     RETURN
     END
```

9.2 Program Data

None.

9.3 Program Results

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