# F08AEFP (PDGEQRF)

# NAG Parallel Library Routine Document

**Note:** before using this routine, please read the Users' Note for your implementation to check for implementation-dependent details. You are advised to enclose any calls to NAG Parallel Library routines between calls to Z01AAFP and Z01ABFP.

# 1 Description

F08AEFP (PDGEQRF) computes the QR factorization of a real m by n matrix  $A_s$  (i.e.,  $A_s = QR$ ), where  $A_s$  is a submatrix of a larger  $m_A$  by  $n_A$  matrix A, i.e.,

$$A_s(1:m,1:n) \equiv A(i_A:i_A+m-1,j_A:j_A+n-1).$$

Note: if  $i_A = j_A = 1$ ,  $m = m_A$  and  $n = n_A$ , then  $A_s = A$ .

The orthogonal matrix Q is not formed explicitly but is represented as a product of elementary reflectors

$$Q = H_0 H_1 \dots H_{k-1}$$
, where  $k = \min(m, n)$ .

Each  $H_{\ell}$  has the form

$$H_{\ell} = I - \tau_{\ell} v_{\ell} v_{\ell}^{T},$$

where  $\tau$  is a real scalar, and v is real vector. No pivoting is performed by F08AEFP (PDGEQRF).

# 2 Specification

```
SUBROUTINE FO8AEFP(M, N, A, IA, JA, IDESCA, TAU, WORK, LWORK, INFO)
ENTRY PDGEQRF(M, N, A, IA, JA, IDESCA, TAU, WORK, LWORK, INFO)
DOUBLE PRECISION A(*), TAU(*), WORK(LWORK)
INTEGER M, N, IA, JA, IDESCA(9), LWORK, INFO
```

The ENTRY statement enables the routine to be called by its ScaLAPACK name.

## 3 Data Distribution

#### 3.1 Definitions

The following definitions are used in describing the data distribution within this document:

the number of rows in the logical processor grid. the number of columns in the logical processor grid.  $n_p$ the row grid coordinate of the calling processor.  $p_r$ the column grid coordinate of the calling processor. the blocking factor for the distribution of the rows of a matrix X. the blocking factor for the distribution of the columns of a matrix X.  $\operatorname{numroc}(\alpha, b_{\ell}, q, s, k)$ a function which gives the number of rows or columns of a distributed matrix owned by the processor with the row or column coordinate q ( $p_r$ or  $p_c$ ), where  $\alpha$  is the total number of rows or columns of the matrix,  $b_{\ell}$  is the blocking factor used  $(M_b^X \text{ or } N_b^X)$ , s is the row or column coordinate of the processor that possesses the first row or column of the distributed matrix and k is either  $n_p$  or  $m_p$ . The Library provides the function Z01CAFP (NUMROC) for the evaluation of this function.  $indxg2p(i_g, b_\ell, q, s, k)$ a function which gives the processor row or column coordinate which possess the row or column index  $i_q$  of the distributed full matrix A.

the evaluation of this function.

The arguments  $b_{\ell}$ , q, s and k have the same meaning as in the function numroc. The Library provides the function Z01CDFP (INDXG2P) for

## 3.2 Global and Local Arguments

The input arguments M, N, IA, JA and the array elements IDESCA(1) and IDESCA(3),...,IDESCA(8) are all global and so must have the same values on entry to the routine on every processor. The output argument INFO is global and so will have the same value on exit from the routine on each processor. The remaining arguments are local.

## 3.3 Distribution Strategy

The matrix A must be partitioned into  $M_b^A$  by  $N_b^A$  rectangular blocks which are stored in an array A in a cyclic 2-d block distribution. This data distribution is described in more detail in the F08 Chapter Introduction. The array TAU is distributed across the processor columns in a cyclic 2-d block fashion, and is aligned with the rows matrix A.

This routine assumes that the data has already been correctly distributed, and if this is not the case will fail to produce correct results. However, the Library provides some utility routines which assist you in distributing data correctly. Descriptions of these routines can be found in Chapters F01 and X04 of the NAG Parallel Library Manual.

# 4 Arguments

Warning: This routine is derived from ScaLAPACK and accurately reflects the specification of the equivalent ScaLAPACK routine. The current release (1.2) of ScaLAPACK imposed a global change in the specification of descriptor arrays. Consequently any applications developed using this routine from Release 1 of the Library will not run correctly, without change, using this Release.

1: M — INTEGER Global Input

On entry: the number of rows of the submatrix  $A_s$ , m.

Constraint:  $0 \le M \le IDESCA(3)$ .

2: N — INTEGER Global Input

On entry: the number of columns of the submatrix  $A_s$ , n.

Constraint:  $0 \le N \le IDESCA(4)$ .

### 3: A(\*) — DOUBLE PRECISION array

Local Input/Local Output

**Note:** array A is formally defined as a vector. However, you may find it more convenient to consider A as a 2-d array of dimension (IDESCA(9), $\gamma$ ), where

 $\gamma \geq \text{numroc}(\text{JA+N-1}, \text{IDESCA}(6), p_c, \text{IDESCA}(8), n_p)$ . See Section 8.

On entry: the local part of the matrix A which may contain parts of the m by n submatrix  $A_s$  to be factorized.

On exit: if  $m \ge n$ , the elements below the diagonal of  $A_s$  are overwritten by details of the orthogonal matrix Q and the upper triangle is overwritten by the corresponding elements of the n by n upper triangular matrix R.

If m < n, the strictly lower triangular part of  $A_s$  is overwritten by details of the orthogonal matrix Q and the remaining elements are overwritten by the corresponding elements of the m by n upper trapezoidal matrix R.

4: IA — INTEGER Global Input

On entry: the row index of matrix A,  $i_A$ , that identifies the first row of the submatrix  $A_s$  to be factorized.

Constraint:  $1 \le IA \le IDESCA(3) - M + 1$ .

5: JA — INTEGER Global Input

On entry: the column index of matrix A,  $j_A$ , that identifies the first column of the submatrix  $A_s$  to be factorized.

Constraint:  $1 \le JA \le IDESCA(4) - N + 1$ .

### **6:** IDESCA(9) — INTEGER array

Local Input

Distribution: the array elements IDESCA(1) and IDESCA(3),...,IDESCA(8) must be global to the processor grid and the elements IDESCA(2) and IDESCA(9) are local to each processor.

On entry: the description array for the matrix A. This array must contain details of the distribution of the matrix A and the logical processor grid.

IDESCA(1), the descriptor type. For this routine, which uses a cyclic 2-d block distribution, IDESCA(1) = 1;

IDESCA(2), the BLACS context (ICNTXT) for the processor grid, usually returned by Z01AAFP;

IDESCA(3), the number of rows,  $m_A$ , of the matrix A;

IDESCA(4), the number of columns,  $n_A$ , of the matrix A;

IDESCA(5), the blocking factor,  $M_b^A$ , used to distribute the rows of the matrix A;

IDESCA(6), the blocking factor,  $N_b^A$ , used to distribute the columns of the matrix A;

IDESCA(7), the processor row index over which the first row of the matrix A is distributed;

IDESCA(8), the processor column index over which the first column of the matrix A is distributed;

IDESCA(9), the leading dimension of the conceptual 2-d array A.

#### Constraints:

```
IDESCA(1) = 1;

IDESCA(3) \geq 0; IDESCA(4) \geq 0;

IDESCA(5) \geq 1; IDESCA(6) \geq 1;

0 \leq \text{IDESCA}(7) \leq m_p - 1; 0 \leq \text{IDESCA}(8) \leq n_p - 1;
```

 $IDESCA(9) \ge max(1, numroc(IDESCA(3), IDESCA(5), p_r, IDESCA(7), m_p)).$ 

### 7: TAU(\*) — DOUBLE PRECISION array

Local Output

**Note:** the dimension of the array TAU must be at least  $\alpha$ , where  $\alpha = \text{numroc}(\beta, \text{IDESCA}(6), p_c, \text{IDESCA}(8), n_p)$  and  $\beta = \text{JA} + \min(M, N) - 1$ .

On exit: the scalar factors  $\tau_{\ell}$  of the elementary reflectors  $H_{\ell}$ .

8: WORK(LWORK) — DOUBLE PRECISION array

Local Workspace/Local Output

On exit: WORK(1) contains the minimum required value of LWORK.

#### 9: LWORK — INTEGER

Local Input

On entry: the dimension of the array WORK as declared in the (sub)program from which F08AEFP (PDGEQRF) is called.

Constraint: LWORK  $\geq$  IDESCA(6)  $\times$  ( $c_1 + c_2 + \text{IDESCA}(6)$ ), where

```
\begin{aligned} c_1 &= \operatorname{numroc}(\mathbf{M} + d_1, \operatorname{IDESCA}(5), p_r, e_1, m_p); \\ c_2 &= \operatorname{numroc}(\mathbf{N} + d_2, \operatorname{IDESCA}(6), p_c, e_2, n_p); \\ d_1 &= \operatorname{mod}(\operatorname{IA} - 1, \operatorname{IDESCA}(5)); \\ d_2 &= \operatorname{mod}(\operatorname{JA} - 1, \operatorname{IDESCA}(6)); \\ e_1 &= \operatorname{indxg2p}(\operatorname{IA}, \operatorname{IDESCA}(5), p_r, \operatorname{IDESCA}(7), m_p); \\ e_2 &= \operatorname{indxg2p}(\operatorname{JA}, \operatorname{IDESCA}(6), p_c, \operatorname{IDESCA}(8), n_p). \end{aligned}
```

This value of LWORK can be calculated by using the Library function Z01CBFP; i.e.,

```
LWORK = Z01CBFP(M,N,IA,JA,IDESCA)
```

### **10:** INFO — INTEGER

Global Output

On exit: INFO = 0 unless the routine detects an error (see Section 5).

# 5 Errors and Warnings

If INFO < 0 an explanatory message is output and control returned to the calling program.

INFO < 0

On entry, one of the arguments was invalid:

if the kth argument is a scalar INFO = -k;

if the kth argument is an array and its jth element is invalid, INFO =  $-(100 \times k + j)$ .

This error occurred either because a global argument did not have the same value on all logical processors, or because its value on one or more processors was incorrect. An explanatory message distinguishes between these two cases.

# 6 Further Comments

The total number of floating-point operations is approximately  $\frac{2}{3}n^2(3m-n)$  if  $m \ge n$  or  $\frac{2}{3}m^2(3n-m)$  if m < n. To solve the system of equations  $A_sX = B_s$ , this routine may be followed by a call to F08AFFP (PDORGQR) which forms Q explicitly. In terms of the QR factorization, the linear system  $A_sX = B_s$  is given by  $QRX = B_s$ , and hence  $RX = Q^TB_s$ . If R is triangular then X may be computed using the PBLAS routine PDTRSM. F08AGFP (PDORMQR) may be used to form  $Q^TB$ .

# 6.1 Algorithmic Detail

For a general m by n matrix A, if  $m \ge n$ , the factorization is given by:

$$A = Q \left( \begin{array}{c} R \\ 0 \end{array} \right)$$

where R is an n by n upper triangular matrix and Q is an m by m orthogonal matrix. It is sometimes more convenient to write the factorization as

$$A = \left( \begin{array}{cc} Q_1 & Q_2 \end{array} \right) \left( \begin{array}{c} R \\ 0 \end{array} \right)$$

which reduces to

$$A = Q_1 R$$

where  $Q_1$  consists of the first n columns of  $Q_1$ , and  $Q_2$  the remaining m-n columns.

If m < n, R is upper trapezoidal, and the factorization can be written

$$A = Q(R_1 R_2)$$

where  $R_1$  is an m by m upper triangular matrix and  $R_2$  is an m by n rectangular matrix.

The matrix Q is not formed explicitly but is represented as a product of  $\min(m, n)$  elementary reflectors. See Anderson *et al.* [1] for details of the block method used by the routine.

#### 6.2 Parallelism Detail

The Level 3 BLAS operations are carried out in parallel within the routine.

### 6.3 Accuracy

The computed factorization is the exact factorization of a nearby matrix A + E, where

$$||E||_2 = \epsilon p(m,n)||A||_2,$$

 $\epsilon$  is **machine precision** and p(m,n) is a modest function of m and n.

### 7 References

- [1] Anderson E, Bai Z, Bischof C, Demmel J, Dongarra J J, Du Croz J J, Greenbaum A, Hammarling S, McKenney A, Ostrouchov S and Sorensen D (1995) *LAPACK Users' Guide* (2nd Edition) SIAM, Philadelphia
- [2] Golub G H and Van Loan C F (1989) *Matrix Computations* Johns Hopkins University Press (2nd Edition), Baltimore

# 8 Example

To solve the linear least-squares problem

$$\min \|Ax^{(i)-c^{(i)}}\|_2$$
 for  $i=1,2$ 

where  $c^{(1)}$  and  $c^{(2)}$  are the columns of the matrix C.

$$A = \begin{pmatrix} -0.57 & -1.28 & -0.39 & 0.25 \\ -1.93 & 1.08 & -0.31 & -2.14 \\ 2.30 & 0.24 & 0.40 & -0.35 \\ -1.93 & 0.64 & -0.66 & 0.08 \\ 0.15 & 0.30 & 0.15 & -2.13 \\ -0.02 & 1.03 & -1.43 & 0.50 \end{pmatrix} \text{ and } C = \begin{pmatrix} -3.15 & 2.19 \\ -0.11 & -3.64 \\ 1.99 & 0.57 \\ -2.70 & 8.23 \\ 0.26 & -6.35 \\ 4.50 & -1.48 \end{pmatrix}.$$

The example uses a 2 by 2 logical processor grid and a 2 by 2 block for both A and C.

**Note:** the listing of the Example Program presented below does not give a full pathname for the data file being opened, but in general the user must give the full pathname in this and any other OPEN statement.

# 8.1 Example Text

```
* FO8AEFP Example Program Text
```

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```
* .. Parameters ..
```

INTEGER NIN, NOUT
PARAMETER (NIN=5,NOUT=6)
INTEGER DT

PARAMETER (DT=1)
INTEGER MB, NB
PARAMETER (MB=2,NB=MB)

INTEGER MMAX, NMAX, LDA, RHSMAX, LDC, IAROW, IACOL,

+ ICROW, ICCOL, LW, LIWORK

PARAMETER (MMAX=6,NMAX=4,LDA=MMAX,RHSMAX=2,LDC=MMAX, + IAROW=0,IACOL=0,ICROW=0,ICCOL=0,LW=100,

LIWORK=100)

\* .. Local Scalars ..

DOUBLE PRECISION RCOND

INTEGER IA, IC, ICNTXT, IFAIL, INFO, JA, JC, LWORKE,

+ LWORKG, M, MP, N, NP, NRHS

LOGICAL ROOT
CHARACTER\*80 FORMAT

\* .. Local Arrays ..

DOUBLE PRECISION A(LDA, NMAX), C(LDC, RHSMAX), TAU(MMAX), WORK(LW)

INTEGER IDESCA(9), IDESCC(9), IWORK(LIWORK)

\* .. External Functions .. DOUBLE PRECISION XO2AJF

INTEGER Z01CBFP, Z01CCFP

LOGICAL ZO1ACFP

EXTERNAL X02AJF, Z01CBFP, Z01CCFP, Z01ACFP

\* .. External Subroutines ..

```
EXTERNAL
                 FO7TGFP, F08AEFP, F08AGFP, PDTRSM, X04BCFP,
                 XO4BDFP, ZO1AAFP, ZO1ABFP
.. Intrinsic Functions ..
INTRINSIC
                MIN
.. Executable Statements ..
ROOT = ZO1ACFP()
IF (ROOT) WRITE (NOUT,*) 'FO8AEFP Example Program Results'
MP = 2
NP = 2
IFAIL = 0
CALL ZO1AAFP(ICNTXT, MP, NP, IFAIL)
OPEN (NIN, FILE='f08aefpe.d')
Skip heading in data file
READ (NIN,*)
READ (NIN,*) M, N, NRHS, FORMAT
IF (M.LE.MMAX .AND. N.LE.NMAX .AND. NRHS.LE.RHSMAX) THEN
   Set array descriptor for A, and read A from data file
   IDESCA(1) = DT
   IDESCA(2) = ICNTXT
   IDESCA(3) = M
   IDESCA(4) = N
   IDESCA(5) = MB
   IDESCA(6) = NB
   IDESCA(7) = IAROW
   IDESCA(8) = IACOL
   IDESCA(9) = LDA
   IFAIL = 0
   CALL XO4BCFP(NIN, M, N, A, 1, 1, IDESCA, IFAIL)
   Set array descriptor for C, and read C from data file
   IDESCC(1) = DT
   IDESCC(2) = ICNTXT
   IDESCC(3) = M
   IDESCC(4) = NRHS
   IDESCC(5) = MB
   IDESCC(6) = NB
   IDESCC(7) = ICROW
   IDESCC(8) = ICCOL
   IDESCC(9) = LDC
   IFAIL = 0
   CALL XO4BCFP(NIN, M, NRHS, C, 1, 1, IDESCC, IFAIL)
   Factorize A
   IA = 1
   JA = 1
   LWORKE = MIN(LW,ZO1CBFP(M,N,IA,JA,IDESCA))
```

```
CALL FO8AEFP(M,N,A,IA,JA,IDESCA,TAU,WORK,LWORKE,INFO)
   IF (INFO.EQ.O) THEN
       Compute solution
      IC = 1
      JC = 1
      LWORKG = MIN(LW, Z01CCFP('L', M, N, IA, JA, IC, JC, IDESCA, IDESCC))
        Apply Q to the right hand sides
      CALL FO8AGFP('L','T',M,NRHS,N,A,IA,JA,IDESCA,TAU,C,IC,JC,
                    IDESCC, WORK, LWORKG, INFO)
      IF (INFO.EQ.O) THEN
            Check the condition of the upper triangle R
         CALL FO7TGFP('1-norm', 'Upper', 'Non-unit', N, A, IA, JA,
                       IDESCA,RCOND,WORK,LW,IWORK,LIWORK,INFO)
         IF (INFO.EQ.O .AND. RCOND.GT.XO2AJF()) THEN
                 Solve the triangular system
            CALL PDTRSM('Left', 'Upper', 'No transpose', 'Non-unit',
                         N, NRHS, 1.0DO, A, IA, JA, IDESCA, C, IC, JC,
                         IDESCC)
            IF (ROOT) THEN
                WRITE (NOUT,*)
                WRITE (NOUT,*) 'Least-squares solution(s).'
                WRITE (NOUT,*)
            END IF
            IFAIL = 0
            CALL XO4BDFP(NOUT, N, NRHS, C, IC, JC, IDESCC, FORMAT, WORK,
                          IFAIL)
         ELSE
            IF (INFO.EQ.O .AND. ROOT) WRITE (NOUT,*)
                 'Matrix is singular to working precision'
         END IF
      END IF
   END IF
END IF
CLOSE (NIN)
IFAIL = 0
CALL ZO1ABFP(ICNTXT, 'N', IFAIL)
STOP
END
```

### 8.2 Example Data

FO8AEFP Example Program Data

```
6 4 2 '(4F12.4)' :Values of M, N, NRHS and FORMAT -0.57 -1.28 -0.39  0.25  
-1.93  1.08 -0.31 -2.14  
2.30  0.24  0.40 -0.35  
-1.93  0.64 -0.66  0.08  
0.15  0.30  0.15 -2.13  
-0.02  1.03 -1.43  0.50 :End of matrix A  
-3.15  2.19  
-0.11 -3.64  
1.99  0.57  
-2.70  8.23  
0.26 -6.35  
4.50 -1.48  :End of matrix C
```

# 8.3 Example Results

FO8AEFP Example Program Results

Least-squares solution(s).

```
1.5146 -1.5838
1.8621 0.5536
-1.4467 1.3491
0.0396 2.9600
```